

# Diffeological spaces as a model for differentiable programs

A tutorial

**Philip Saville, University of Oxford**  
these slides available at [philipsaville.co.uk](http://philipsaville.co.uk)

- (1) What questions does denotational semantics study?
- (2) Why are cartesian closed categories so important?
- (3) Where do diffeological spaces come in?

# What does programming language theory study?

We want programs that are:

efficient, fast, and correct

We ask:

- (1) When are programs interchangeable?
- (2) How should we think about programs?

gets interesting when programs have effects  
= interaction with the world

# When are programs interchangeable?

example 1

flips a coin with bias  $p \in [0,1]$

let b = flip(p);  
return b;

more efficient

not correct!

return (heads)

let b = flip(p);  
if b == heads:  
  then return (heads);  
  else return (heads);

more efficient

correct!

return (heads)

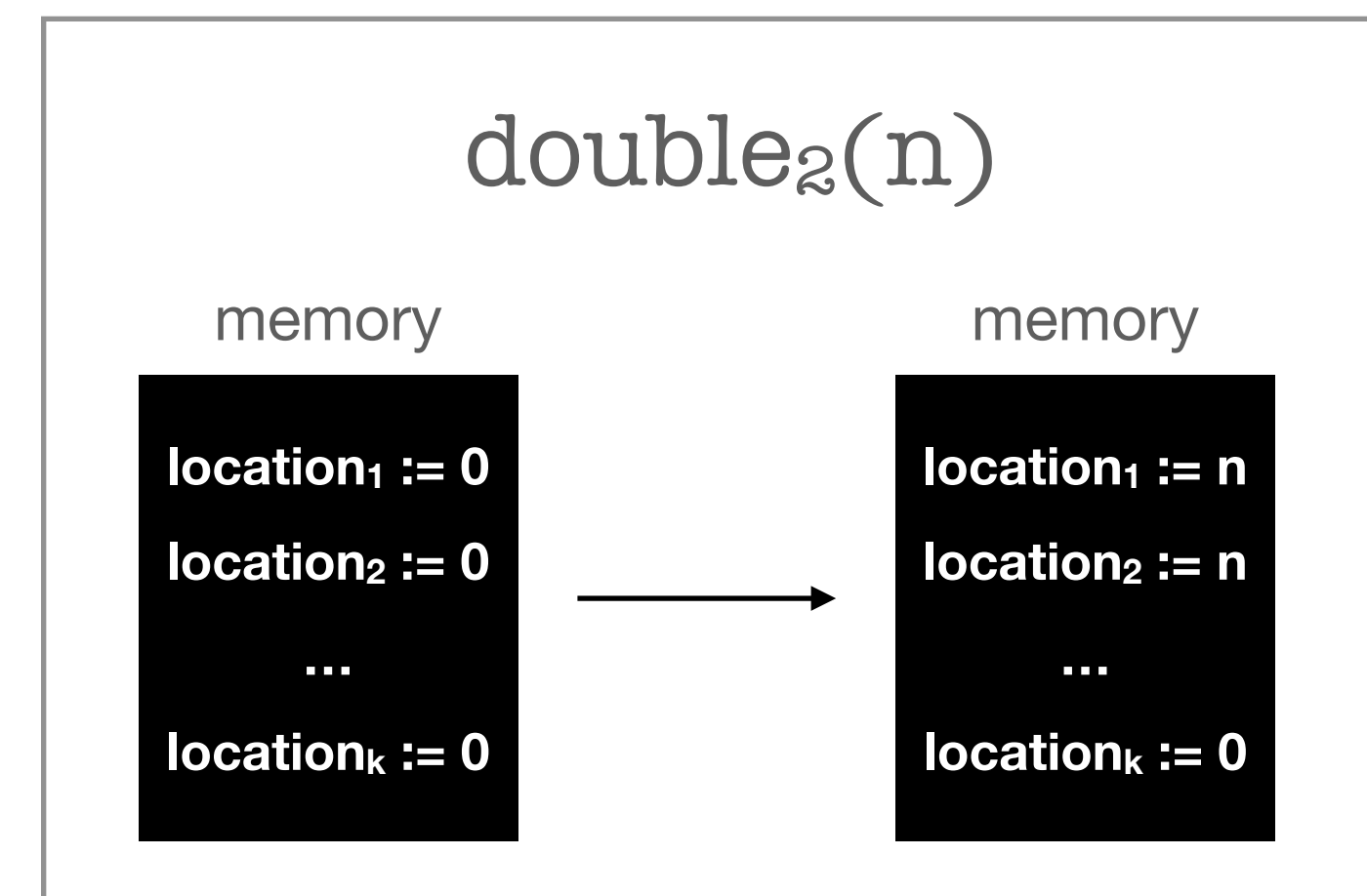
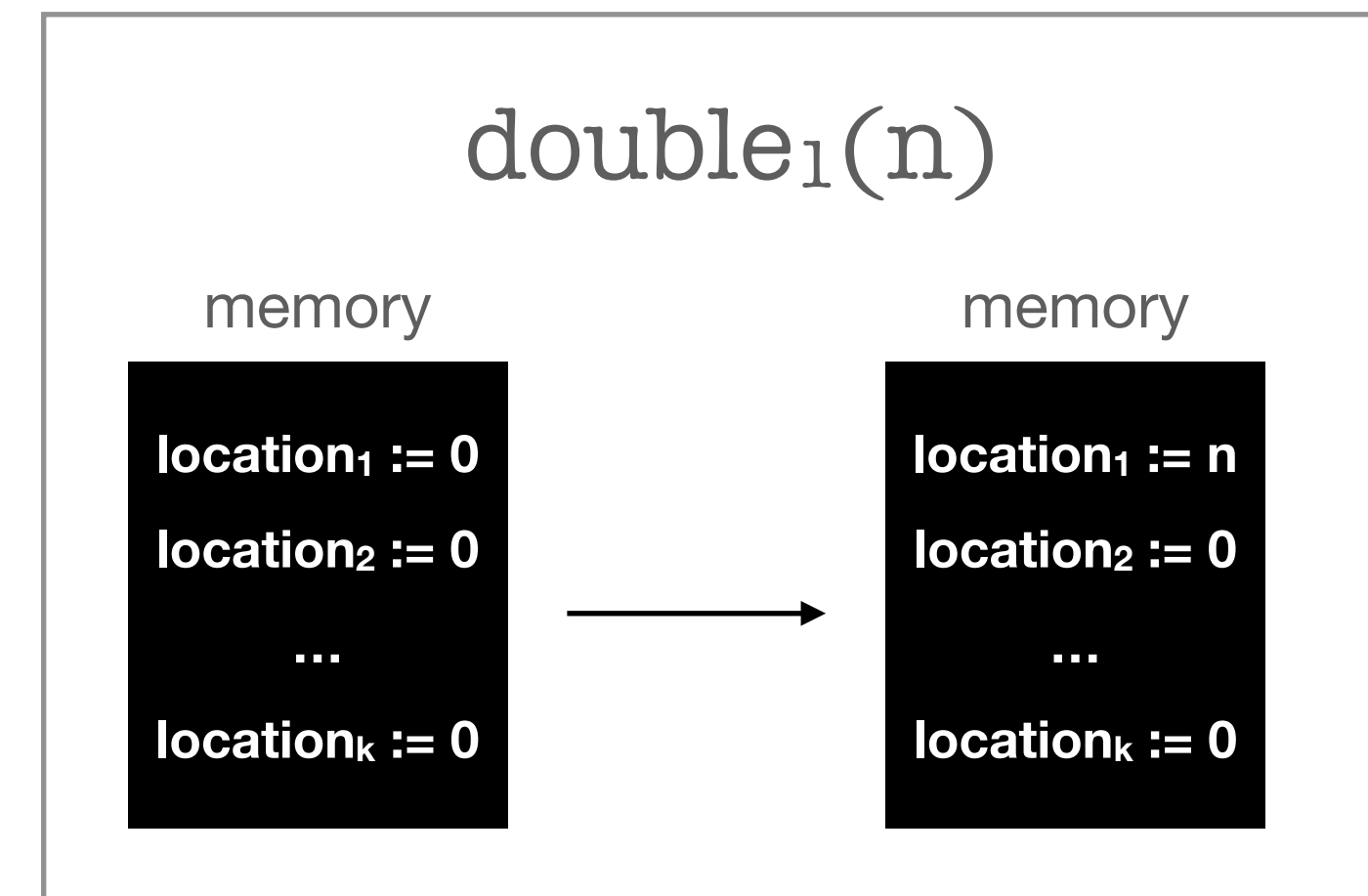


# When are programs interchangeable?

example 2

```
fun double1(n):  
  set_memory location1 := n;  
  return (  
    get_memory (location1)  
    + get_memory (location1)  
  );
```

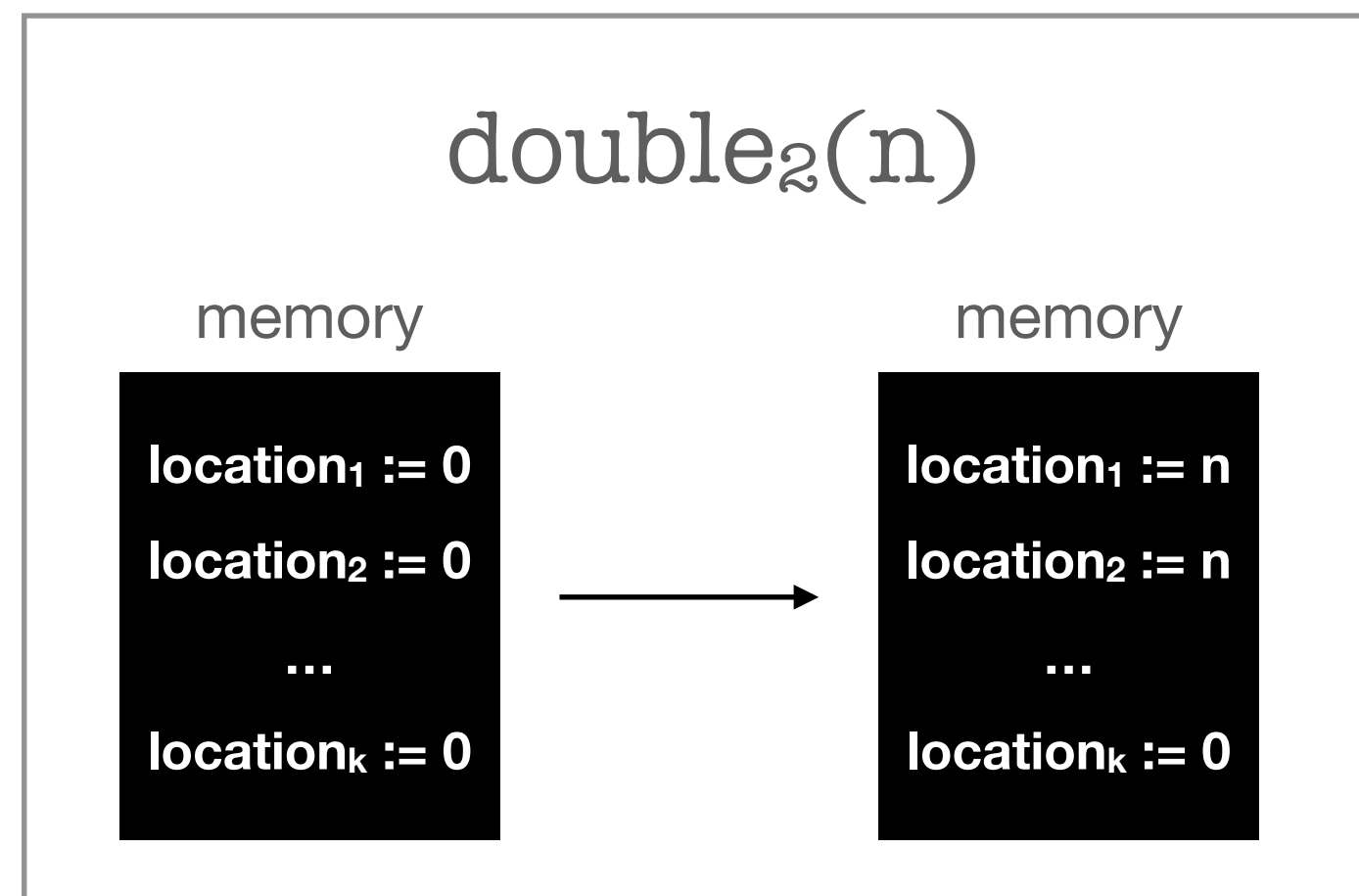
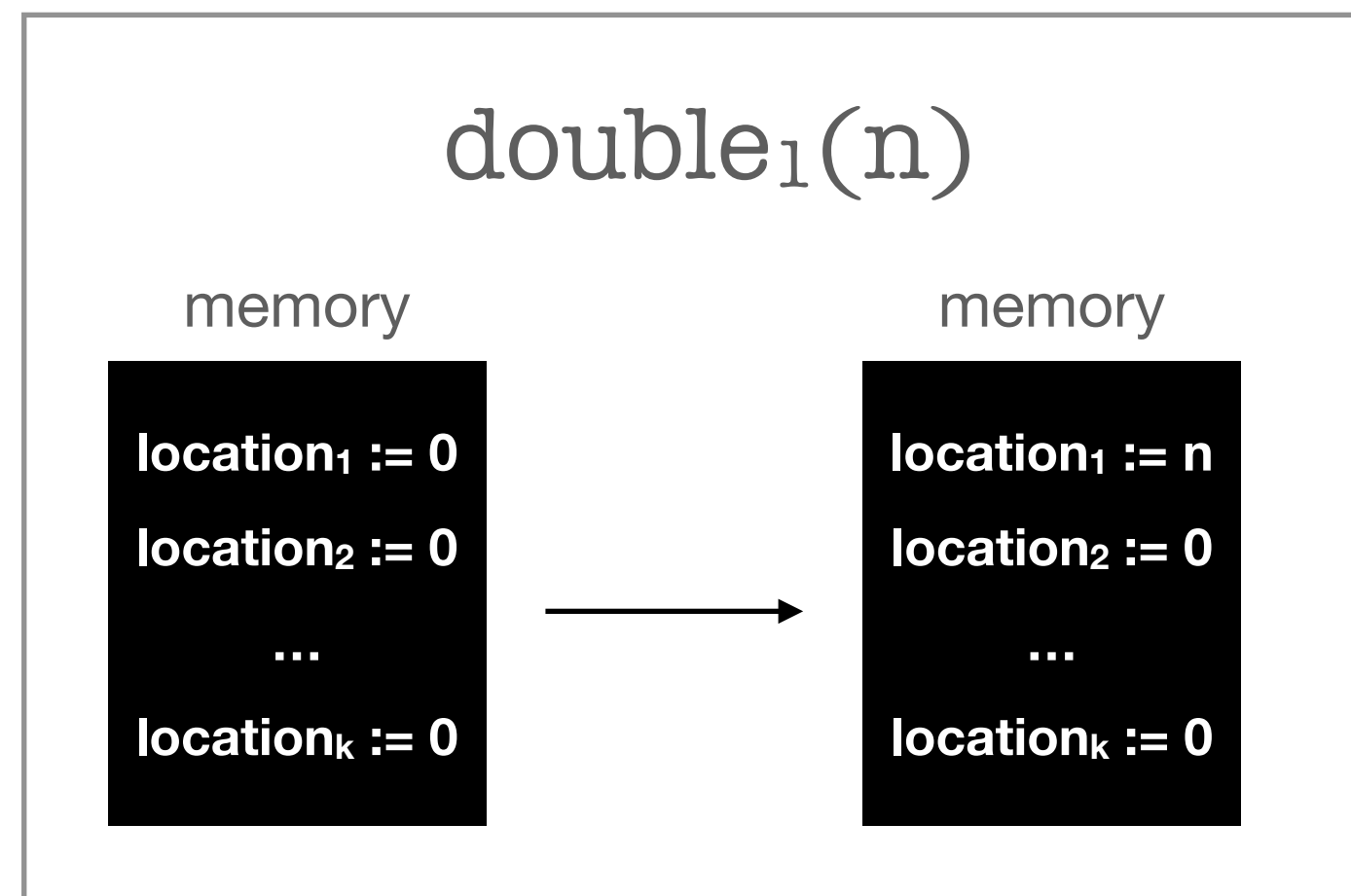
```
fun double2(n):  
  set_memory location1 := n  
  set_memory location2 := n  
  return (  
    get_memory (location1)  
    + get_memory (location2)  
  );
```



# When are programs **interchangeable**?

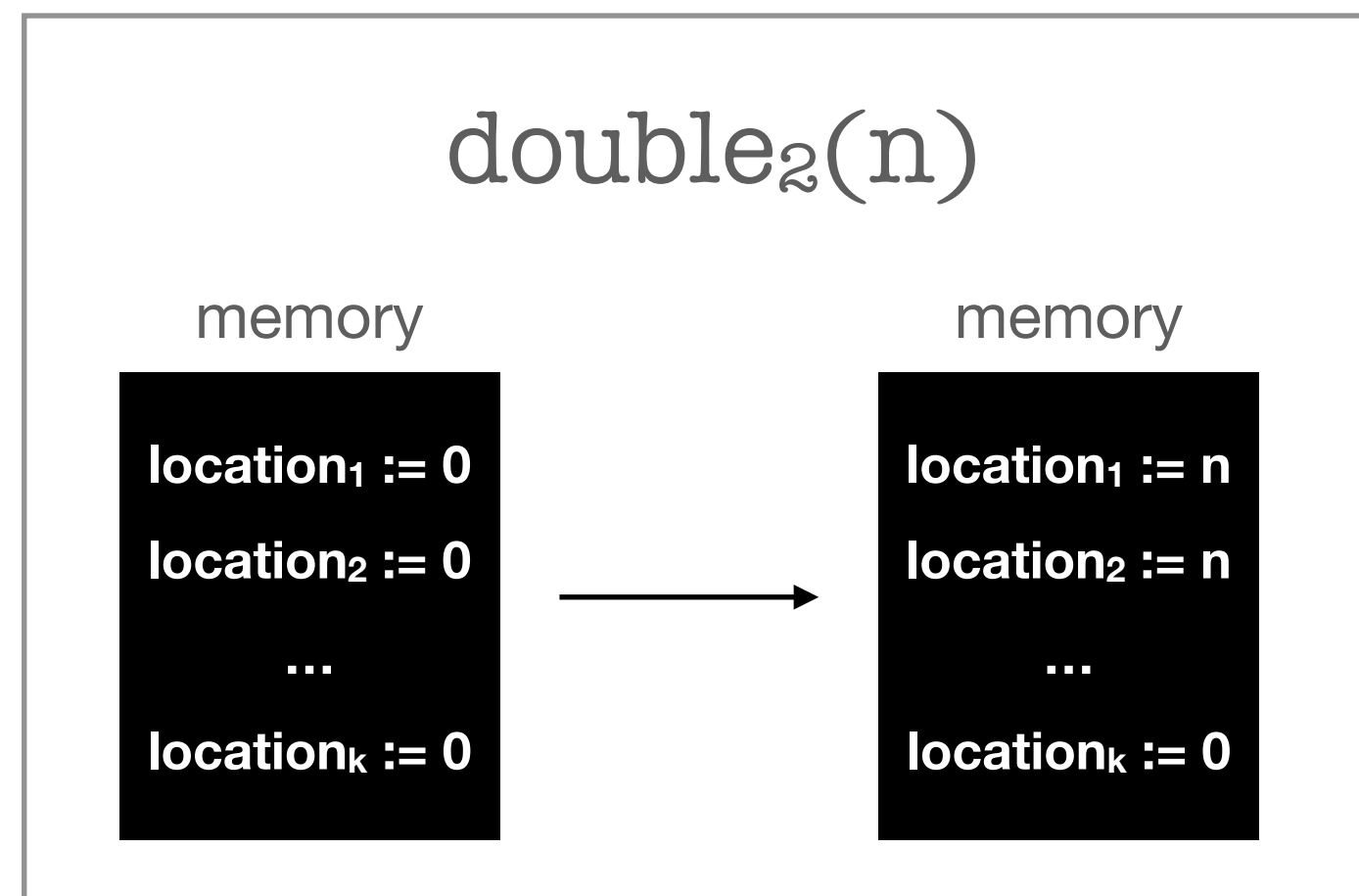
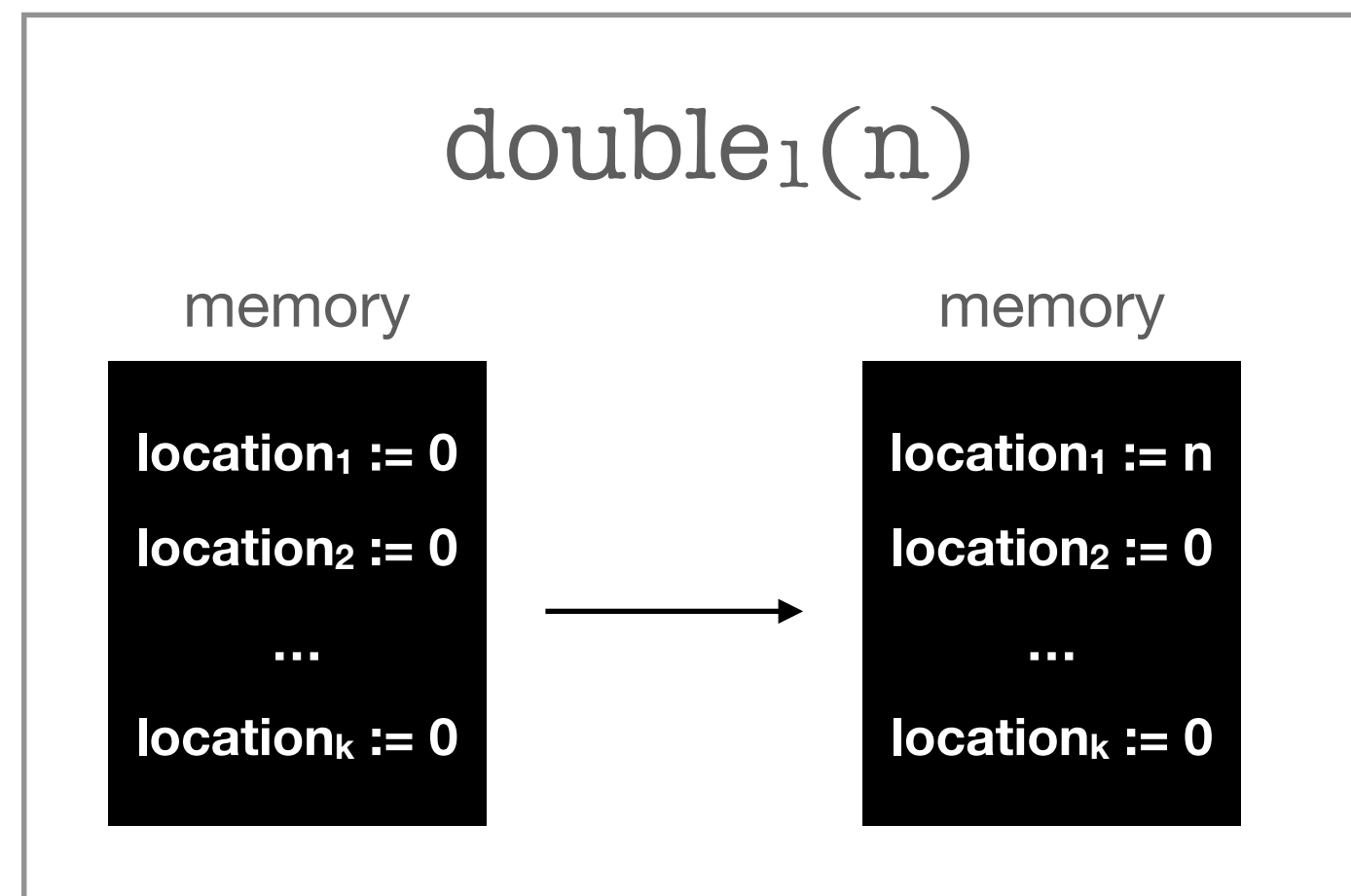
example 2

equal as **functions** but not as **programs**!  
→ we can observe a difference in behaviour



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example 2

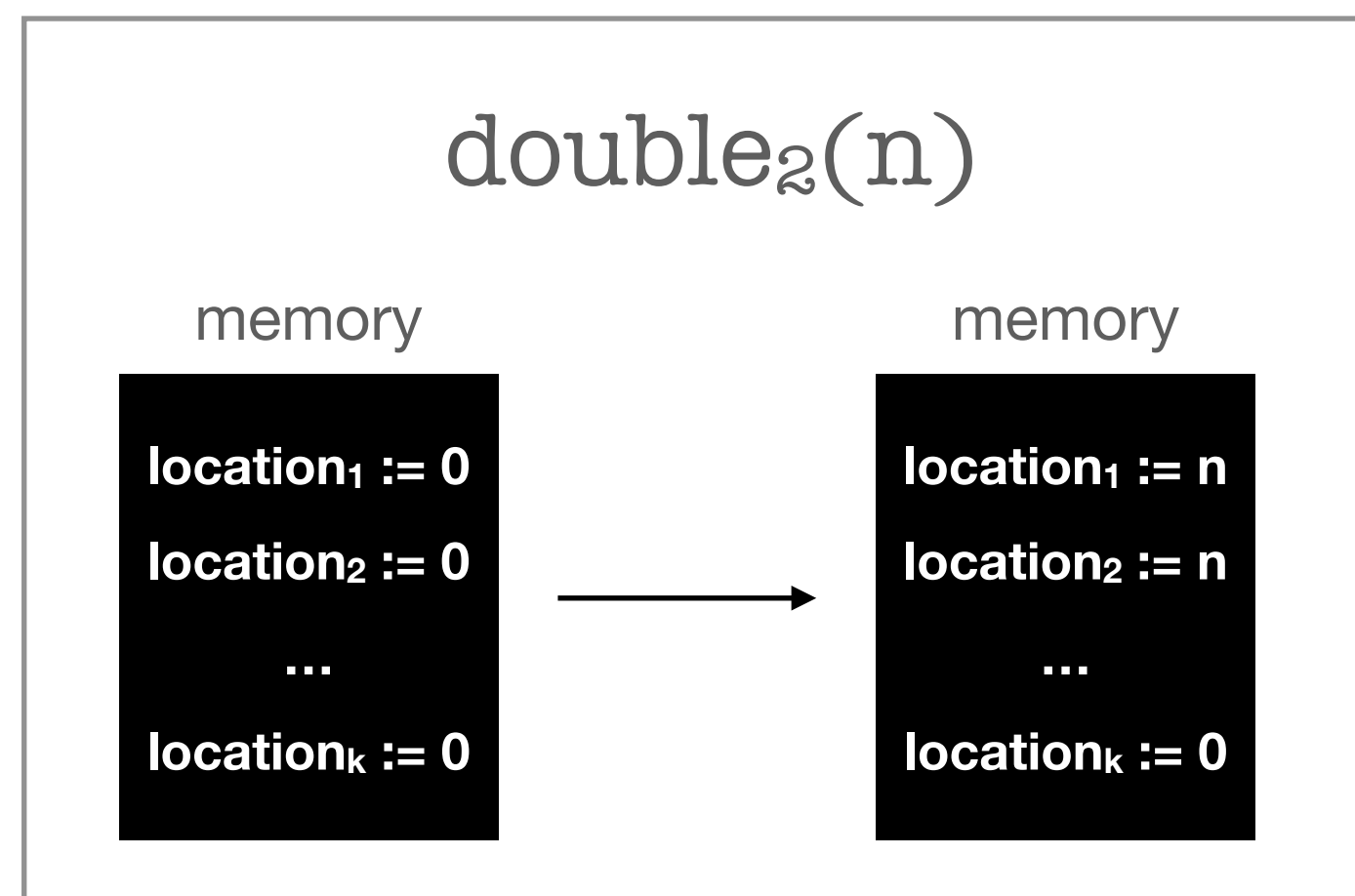
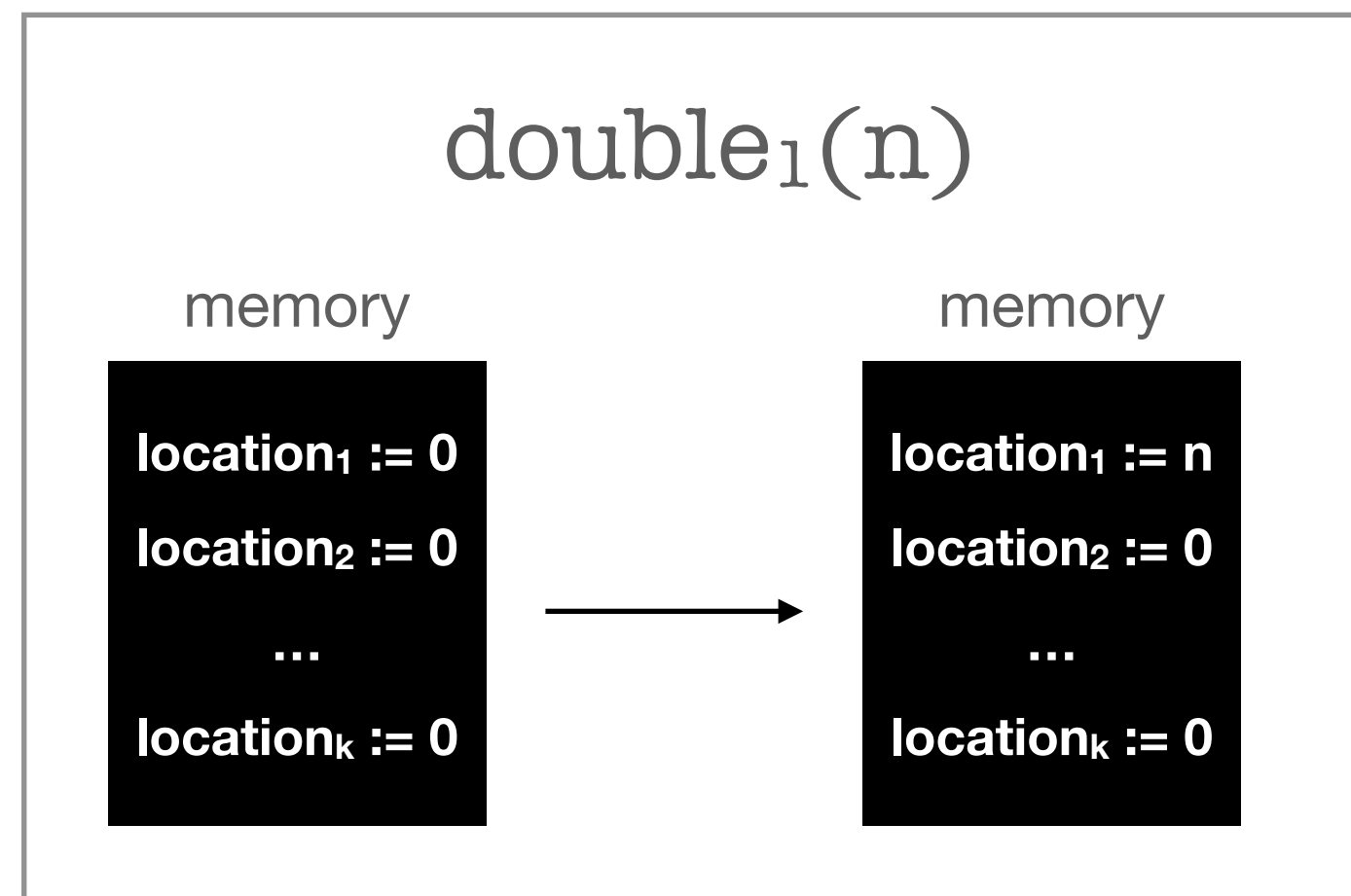


equal as **functions** but not as **programs**!  
 $\leadsto$  we can observe a difference in behaviour

$$\forall n . \text{double}_1(n) = \text{double}_2(n)$$

# When are programs interchangeable?

example 2



equal as **functions** but not as **programs**!  
→ we can observe a difference in behaviour

$$\forall n . \text{double}_1(n) = \text{double}_2(n)$$

**but** can distinguish them by looking at memory:

```
doublei(2);  
let n = get_memory location2;  
if n > 0:  
  then return (false);  
  else return (true);
```

i = 1      i = 2

return (true);      return (false);

# When are programs **interchangeable**?

programs  $P$  and  $Q$  are **observationally equivalent**  
if there's no way to observe a difference in behaviour

any program  $\mathcal{C}[P]$  containing  $P$  gives a result  
iff  $\mathcal{C}[Q]$  gives the same result

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observational equivalence

generally harder than  
function equality  
depends on the  
language's features

depends on how  
programs run



# Observational equivalence in the real world

how do you prove you're not Banksy?

**A town councillor has resigned, blaming people who falsely accused him of being the world famous artist Banksy.**

Pembroke Dock councillor William Gannon said the "quite ridiculous" claims were made on several social media pages.

In his resignation letter he claimed this was "undermining my ability to do the work" of a councillor.

Mr Gannon has since made an "I am not Banksy" badge to avoid any confusion and said he would now be returning to his former role of community artist.

He said the allegations meant people were "asking me to prove who I am not and that's almost impossible to do".

<https://www.bbc.co.uk/news/uk-wales-61552865>





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if there's no way to tell them apart, they must be the same!



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# How should we think about programs?

```
fun add(x, y):  
  return (x + y)
```

a function  $\mathbb{N} \times \mathbb{N} \rightarrow \mathbb{N}$

# How should we think about programs?

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fun add(x, y):  
  return (x + y)
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```
fun divide(x, y):  
  return (x / y)
```

a function  $\mathbb{N} \times \mathbb{N} \rightarrow \mathbb{N}$

a function  $\mathbb{Z} \times \mathbb{Z}_{\neq 0} \rightarrow \mathbb{Q}$

a function  $\mathbb{Z} \times \mathbb{Z} \rightarrow \mathbb{Q} + \{\text{fail}\}$

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fun add(x, y):  
  return (x + y)
```

```
fun divide(x, y):  
  return (x / y)
```

```
fun print_and_return(x):  
  print "hello";  
  return x;
```

a function  $\mathbb{N} \times \mathbb{N} \rightarrow \mathbb{N}$

a function  $\mathbb{Z} \times \mathbb{Z}_{\neq 0} \rightarrow \mathbb{Q}$

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a function  $\mathbb{N} \rightarrow \{a, b, \dots, z\}^* \times \mathbb{N}$   
 $x \mapsto (\text{hello}, x)$

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let b = flip(p);  
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a probability distribution on  
 $\{\text{heads}, \text{tails}\}$

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fun divide(x, y):  
  return (x / y)
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```
fun print_and_return(x):  
  print "hello";  
  return x;
```

```
let b = flip(p);  
return b;
```

```
normalise(  
  let x = sample(bernoulli(0.8));  
  let r = (if x then 10 else 3);  
  observe 0.45 from exponential(r)  
  return(x)  
)
```

a function  $\mathbb{N} \times \mathbb{N} \rightarrow \mathbb{N}$

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a probability distribution on  
 $\{\text{heads}, \text{tails}\}$

some measurable function (??)



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observational equivalence

generally harder than  
function equality  
depends on the  
language's features

depends on how  
programs run

some kind  
of function?

need something beyond set-theoretic  
functions to model richer features!



uses ideas from:

- topology
- logic
- order theory

# What does programming language theory study?

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The denotational semantics perspective:

- (1) Assign every program  $P$  a meaning  $\llbracket P \rrbracket$
- (2) Reason about equality of programs via their meaning
- (3) The semantic model tells you what programs ‘really are’

# Coming up next

1. Introduce an idealised functional programming language
  2. Explain its semantic interpretation in CCCs
- 

3. Introduce differentiable programming
4. Explain the interpretation in Diff

# What is a program?



something modelled by a Turing machine

memory you can read  
to & write from

Java, C, C++, ...

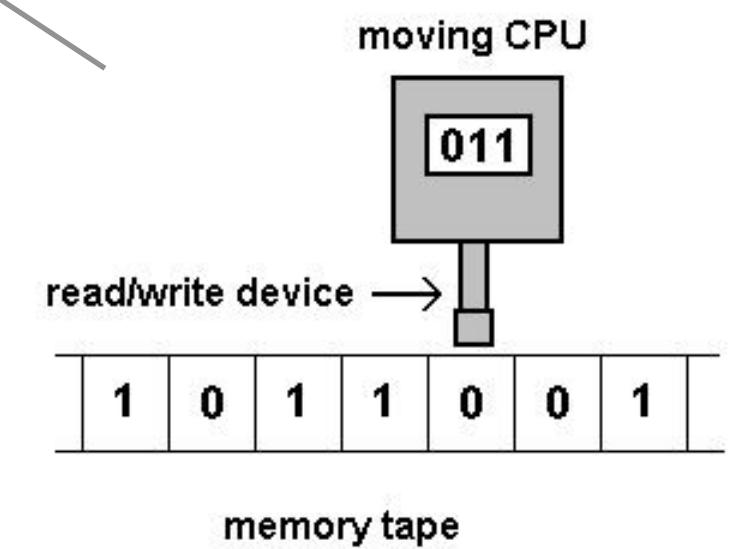
```
n1 = 0
n2 = 1
steps_taken = 0
while (steps_taken < 100) {
    fib = n1 + n2
    n1 = n2
    n2 = fib
    steps_taken = steps_taken + 1
}
```



a kind of function

OCaml, Haskell,  
Standard ML,...

```
fib 0 = 0
fib 1 = 1
fib n = fib (n-1) + fib (n-2)
```



So a **functional programming language** lets you

- form functions
- evaluate functions at arguments

# How do we define functions?



function **body**

may not use  $x$ , eg  $f(x) = 3$

may contain free variables, eg  
 $f(x) = 3y + x$

$$f(x) = x^3 + x^2 + 1$$

**bound** variable

the  $x$  matters: if

$$g(y) = 3y^3 + y^2 + 1$$

$$h(y) = 3x^3 + x^2 + 1$$

then  $f = g$  but  $h$  is a constant function

every other  
variable is **free**

A **functional programming language** lets you

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evaluating = **substituting** for bound variable

$$\begin{aligned} f(3) &= (x^3 + x^2 + 1)[x \mapsto 3] \\ &= 3^3 + 3^2 + 1 \end{aligned}$$



# How do we define functions?



function **body**

may not use  $x$ , eg  $f(x) = 3$

may contain free variables, eg  
 $f(x) = 3y + x$

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$$f(x) = x^3 + x^2 + 1 \text{ in } \mathbb{R} \text{ whenever } x \in \mathbb{R}$$

**bound** variable  $x \in \mathbb{R}$

the  $x$  matters: if

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$$h(y) = 3x^3 + x^2 + 1$$

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# How do we define functions?



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function **body**  
 $x^3 + x^2 + 1$  is a program

---

$(x \mapsto x^3 + x^2 + 1)$  is a program

**bound** variable

every other  
variable is **free**

$(x \mapsto x^3 + x^2 + 1)$  is a program      3 is a program

---

$(x \mapsto x^3 + x^2 + 1)(3)$  is a program

evaluating = **substituting** for bound variable

$(x \mapsto x^3 + x^2 + 1)(3) \rightsquigarrow 3^3 + 3^2 + 1$

extensionality:  $f = (x \mapsto f(x))$

$(x \mapsto (x^3 + x_{28}^2 + 1)(x)) \rightsquigarrow (x \mapsto x^3 + x^2 + 1)$



# How do we define functions?

the  $\lambda$ -calculus

$$\lambda x . f(x) = (x \mapsto f(x))$$



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function body  
 $x^3 + x^2 + 1$  is a program

---

$\lambda x . x^3 + x^2 + 1$  is a program

|  
bound variable

every other  
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$\lambda x . x^3 + x^2 + 1$  is a program      3 is a program

---

$(\lambda x . x^3 + x^2 + 1)(3)$  is a program

evaluating = substituting for bound variable

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the simply-typed  $\lambda$ -calculus

$$\lambda x . f(x) = (x \mapsto f(x))$$



A functional programming language lets you

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function body  
 $x^3 + x^2 + 1$  is a program of type  $\mathbb{R}$

---

$\lambda x . x^3 + x^2 + 1$  is a program of type  $\mathbb{R} \rightarrow \mathbb{R}$

bound variable

every other  
variable is free

$\lambda x . x^3 + x^2 + 1$  is a program of type  $\mathbb{R} \rightarrow \mathbb{R}$       3 is a program of type  $\mathbb{R}$

---

$(\lambda x . x^3 + x^2 + 1)(3)$  is a program of type  $\mathbb{R}$

evaluating = substituting for bound variable

$$(\lambda x . x^3 + x^2 + 1)(3) \rightsquigarrow 3^3 + 3^2 + 1$$

extensionality:  $f = (x \mapsto f(x))$

$$(x \mapsto (x^3 + x_0^2 + 1)(x)) \rightsquigarrow (x \mapsto x^3 + x^2 + 1)$$

# How do we define functions?

the simply-typed  $\lambda$ -calculus

$$\lambda x . f(x) = (x \mapsto f(x))$$

function **body**

$$\frac{P \text{ is a program of type } B \quad x \text{ is a variable of type } A}{\lambda x . P \text{ is a program of type } A \rightarrow B} \text{abstraction}$$

**bound** variable  
every other  
variable is **free**

$$\frac{P \text{ is a program of type } A \rightarrow B \quad Q \text{ is a program of type } A}{P(Q) \text{ is a program of type } B} \text{application}$$

evaluating = **substituting** for bound variable

$$(\lambda x . P)(Q) \rightsquigarrow_{\beta} P[x \mapsto Q]$$

extensionality:  $f = (x \mapsto f(x))$

$$P \rightsquigarrow_{\eta} \lambda x . P(x)$$



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# How do we define functions?



the simply-typed  $\lambda$ -calculus

$$\lambda x . f(x) = (x \mapsto f(x))$$

$x$  is a variable

$x$  is a program

$P : B$  is a program

$x : A$  is a variable

abstraction

$\lambda x . P : A \rightarrow B$  is a program

$P : A \rightarrow B$  is a program

$Q : A$  is a program

application

$P(Q) : B$  is a program

evaluating = substituting for bound  $x$

$$P(Q) \sim_{\beta} P[x \mapsto Q]$$

= running the program

extensionality

$$P \sim_{\eta} \lambda x . P(x)$$

$$f = (x \mapsto f(x))$$

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$$\frac{x \text{ is a variable}}{x \text{ is a program}}$$

$$\frac{P : B \text{ is a program} \quad x : A \text{ is a variable}}{\text{abstraction} \quad \lambda x . P : A \rightarrow B \text{ is a program}}$$

$$\frac{P : A \rightarrow B \text{ is a program} \quad Q : A \text{ is a program}}{P(Q) : B \text{ is a program}} \quad \text{application}$$

$$\begin{aligned} \text{evaluating} &= \text{substituting for bound } x \\ P(Q) &\sim_{\beta} P[x \mapsto Q] \\ &= \text{running the program} \end{aligned}$$

$$\begin{aligned} \text{extensionality} \\ P &\sim_{\eta} \lambda x . P(x) \\ f &= (x \mapsto f(x)) \end{aligned}$$

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$$f : A \rightarrow B$$

$$x : A$$

$$f(x) : B$$

$$\lambda x . f(x) : A \rightarrow B$$

$$\lambda f . \lambda x . f(x) : (A \rightarrow B) \rightarrow (A \rightarrow B)$$

$$\begin{aligned} \text{eval} : (A \Rightarrow B) \times A &\rightarrow B \\ (f, x) &\mapsto f(x) \end{aligned}$$

$$\text{via currying } X \rightarrow (A \Rightarrow B) \cong (X \times A) \rightarrow B$$

# How do we define functions?



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$$\lambda x . f(x) = (x \mapsto f(x))$$

$$\frac{x \text{ is a variable}}{x \text{ is a program}}$$

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$$\frac{\frac{\frac{f : A \rightarrow B}{x : A}}{f(x) : B}}{\lambda x . f(x) : A \rightarrow B}}{\lambda f . \lambda x . f(x) : (A \rightarrow B) \rightarrow (A \rightarrow B)}$$

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$$\frac{\frac{\frac{\frac{g : B \rightarrow C}{f : A \rightarrow B} \quad x : A}{f(x) : B}}{g(f(x)) : C}}{\lambda x . g(fx) : A \rightarrow C}}{\lambda f . \lambda x . g(fx) : (A \rightarrow B) \rightarrow (A \rightarrow C)}}{\lambda g . \lambda f . \lambda x . g(fx) : (B \rightarrow C) \rightarrow ((A \rightarrow B) \rightarrow (A \rightarrow C))}$$

$$\begin{aligned} \text{comp} : (B \Rightarrow C) \times (A \Rightarrow B) &\rightarrow (A \Rightarrow C) \\ (g, f) &\mapsto g \circ f \end{aligned}$$

# Things we can't do

## the $\lambda$ -calculus

$$\lambda x . f(x) = (x \mapsto f(x))$$

$$\frac{x \text{ is a variable}}{x \text{ is a program}}$$

$$\frac{P \text{ is a program}}{\lambda x . P \text{ is a program}} \quad \text{abstraction}$$

$$\text{extensionality: } f = (x \mapsto f(x)) \\ P \sim_{\eta} \lambda x . P(x)$$

$$\frac{P \text{ is a program} \quad Q \text{ is a program}}{P(Q) \text{ is a program}} \quad \text{application}$$

$$\text{evaluating} = \text{substituting for bound variable} \\ P(Q) \sim_{\beta} P[x \mapsto Q] \\ = \text{running the program}$$



A **functional programming language** lets you

- form functions
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Note there's no restrictions on either rule!

$$\frac{f \text{ is a variable}}{f \text{ is a program}} \\ \frac{f(f) \text{ is a program}}{\lambda f . f(f) \text{ is a program}}$$

Looping, recursion, ...

$$(\lambda f . f(f)) (\lambda f . f(f)) \sim (\lambda f . f(f)) [f \mapsto (\lambda f . f(f))] \\ = (\lambda f . f(f)) (\lambda f . f(f))$$

Encode Peano arithmetic

$$1 := (\lambda f . \lambda f . f(x)) \\ 2 := (\lambda f . \lambda f . f(fx)) \\ \text{plus} := (\lambda m . \lambda n . \lambda f . \lambda x . mf(nfx))$$



# Adding primitives

the simply-typed  $\lambda$ -calculus

$$\lambda x . f(x) = (x \mapsto f(x))$$



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$$\frac{}{\underline{n} : \text{nat}} \quad (n \in \mathbb{N})$$

$$\frac{}{\text{true} : \text{bool}} \quad \frac{}{\text{false} : \text{bool}}$$

$$\frac{}{\text{flip}() : \text{bool}}$$

# Adding primitives

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## What about plus, if etc?

$$\text{plus} : \mathbb{N} \times \mathbb{N} \rightarrow \mathbb{N}$$

$$\text{if} : 2 \times \mathbb{N} \times \mathbb{N} \rightarrow \mathbb{N}$$

$$\frac{}{\underline{n} : \text{nat}} \quad (n \in \mathbb{N})$$

$$\frac{}{\text{true} : \text{bool}} \quad \frac{}{\text{false} : \text{bool}}$$

$$\frac{}{\text{flip}() : \text{bool}}$$

$$\text{if}(i, n, m) = \begin{cases} n & \text{if } i = 0 \\ m & \text{if } i = 1 \end{cases}$$

# Adding primitives

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What about plus, if etc?

$$\text{plus} : \mathbb{N} \times \mathbb{N} \rightarrow \mathbb{N}$$

$$\text{if} : 2 \times \mathbb{N} \times \mathbb{N} \rightarrow \mathbb{N}$$

$$\frac{}{\underline{n} : \text{nat}} \quad (n \in \mathbb{N})$$

$$\frac{}{\text{true} : \text{bool}} \quad \frac{}{\text{false} : \text{bool}}$$

$$\frac{}{\text{flip}() : \text{bool}}$$

$$\text{if}(i, n, m) = \begin{cases} n & \text{if } i = 0 \\ m & \text{if } i = 1 \end{cases}$$

**Option 1:**  $\text{if}(b, n, m) : \text{nat}$  (where  $b : \text{bool}, n : \text{nat}, m : \text{nat}$ )

**Option 2:** add a type to model  $\mathbb{N} \times \mathbb{N}$

in general: introduce new types for new kinds of structure

# Adding product types

the simply-typed  $\lambda$ -calculus

$$\lambda x . f(x) = (x \mapsto f(x))$$



A functional programming language lets you

- form functions
- evaluate functions at arguments

How does  $X \times Y$  behave in Set?

$$\frac{x \in X \quad y \in Y}{(x, y) \in X \times Y} \text{ pair}$$

$$\frac{p \in A_1 \times A_2}{\pi_i(p) \in A_i} \text{ proj } (i = 1, 2)$$

project out a pair

$$\pi_i(x_1, x_2) = x_i$$

extensionality: a pair is determined by its projections

$$p = (\pi_1(p), \pi_2(p))$$

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$$\frac{P_1 : A_1 \quad P_2 : A_2}{\langle P_1, P_2 \rangle : A_1 \times A_2} \text{ pair}$$

$$\frac{P : A_1 \times A_2}{\pi_i(P) : A_i} \text{ proj } (i = 1, 2)$$

project out a pair

$$\pi_i \langle P_1, P_2 \rangle \rightsquigarrow_\beta P_i$$

extensionality: a pair is determined by its projections

$$P \rightsquigarrow_\eta \langle \pi_1(P), \pi_2(P) \rangle$$



# The simply-typed $\lambda$ -calculus with products and primitives

= the simplest (typed)  
functional programming language

can also add sums / disjoint unions, lists, recursion, ....

+ any others you might want!

$$\frac{x : A \quad P : B}{\lambda x . P : A \rightarrow B} \text{abstraction}$$

$$\frac{P : A \rightarrow B \quad Q : A}{P(Q) : B} \text{application}$$

evaluating = substituting for bound variable

$$(\lambda x . P)(Q) \rightsquigarrow_{\beta} P[x \mapsto Q]$$

= running the program

extensionality:  $f = (x \mapsto f(x))$

$$P \rightsquigarrow_{\eta} \lambda x . P(x)$$

$$\begin{array}{ccc} \overline{\text{true} : \text{bool}} & \overline{\text{false} : \text{bool}} & \overline{\text{if}(b, n, m) : \text{nat}} \\[1em] \overline{\text{flip}() : \text{bool}} & \frac{(n \in \mathbb{N})}{\underline{n} : \text{nat}} & \overline{\text{plus} : \text{nat} \times \text{nat} \rightarrow \text{nat}} \end{array}$$

$$\begin{array}{l} \text{plus}(\underline{3}, \underline{2}) : \text{nat} \\ \text{if}(\text{true}, \underline{3}, \underline{2}) : \text{nat} \end{array}$$

$$\frac{P_1 : A_1 \quad P_2 : A_2}{\langle P_1, P_2 \rangle : A_1 \times A_2} \text{pair}$$

project out a pair

$$\pi_i(P_1, P_2) \rightsquigarrow_{\beta} P_i$$

extensionality: a pair is determined by its projections

$$P \rightsquigarrow_{\eta} (\pi_1(P), \pi_2(P))$$

$$\frac{P : A_1 \times A_2}{\pi_i(P) : A_i} \text{proj } (i = 1, 2)$$

+ a 'unit' type

# $\beta$ -reduction = running the program

$$\begin{aligned} & (\lambda p : \text{nat} \times \text{nat} \rightarrow \text{bool} . \lambda t : \text{nat} \times \text{nat} . \text{if}(p(t), \underline{2}, \underline{3}))(\text{greater\_than})(\langle \underline{5}, \underline{6} \rangle) \\ & \quad \rightsquigarrow_{\beta} (\lambda t : \text{nat} \times \text{nat} . \text{if}(\text{greater\_than}(t), \underline{2}, \underline{3}))(\langle \underline{5}, \underline{6} \rangle) \\ & \quad \rightsquigarrow_{\beta} \text{if}(\text{greater\_than}\langle \underline{5}, \underline{6} \rangle, \underline{2}, \underline{3}) \\ & \quad \rightsquigarrow_{\beta} \underline{3} \end{aligned}$$

# The magic of higher-order functions

higher-order functions = functions of type  $(A \rightarrow B) \rightarrow C$

higher-order functions let you re-use code in a very efficient way

$$P : ((\text{nat} \rightarrow \text{bool}) \times (\text{nat} \rightarrow \text{nat})) \rightarrow \text{nat}$$

acts on an arbitrary predicate and arbitrary endo-function on nat

$$\begin{aligned} \text{eval} : (A \Rightarrow B) \times A &\rightarrow B \\ (f, x) &\mapsto f(x) \end{aligned}$$

$$\lambda p . (\pi_1(p)) (\pi_2(p)) : (A \rightarrow B) \times A \rightarrow B$$

$$\begin{aligned} \pi_1(p) &: (A \rightarrow C) \\ \pi_2(p) &: A \end{aligned}$$

$$\begin{aligned} \text{comp} : (B \Rightarrow C) \times (A \Rightarrow B) &\rightarrow (A \Rightarrow C) \\ (g, f) &\mapsto g \circ f \end{aligned}$$

$$\lambda f . \lambda x . (\pi_1(f)) (\pi_2(f)(x)) : ((B \rightarrow C) \times (A \rightarrow B)) \rightarrow (A \rightarrow C)$$

$$\begin{aligned} \pi_1(f) &: (B \rightarrow C) \\ \pi_2(f) &: (A \rightarrow B) \\ \pi_2(f)(x) &: B \\ (\pi_1(f)) (\pi_2(f)(x)) &: C \\ \lambda x . (\pi_1(f)) (\pi_2(f)(x)) &: A \rightarrow C \end{aligned}$$

Note the **observable behaviour** is about when values get returned

this is what we care about!

# What does programming language theory study?

We want programs that are:

efficient, fast, and correct

We ask:

- (1) How should we think about programs?
- (2) When are programs interchangeable?

terms in some version of simply-typed  $\lambda$ -calculus

Two notions of equality:

- (1) “equality as functions”
- (2) “equality as programs”

= same behaviour no matter  
what program you put them into



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$\beta\eta$ -equality  $=_{\beta\eta}$ : the congruence generated by  $\sim_{\beta} \cup \sim_{\eta}$

**observational equivalence:**  $P \simeq_{\text{obs}} Q$  iff whatever program  $C[_]$  of type `bool` or `nat` we put them in,  $C[P]$  and  $C[Q]$  have the same behaviour

$$P =_{\beta\eta} Q \implies P \simeq_{\text{ctx}} Q$$

converse is false!

$$(\lambda x . P)(Q) =_{\beta\eta} P[x \mapsto Q]$$

$$P =_{\beta\eta} \lambda x . P(x)$$

$$\pi_i(\langle P_1, P_2 \rangle) =_{\beta\eta} P_i \quad (i = 1, 2)$$

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for every program  $C[_]$  with a 'hole' such that  $C[P], C[Q] : \text{nat}$  or  $C[P], C[Q] : \text{bool}$ , we have  
 $C[P]$  terminates with output  $V$  and effect  $E \iff C[Q]$  terminates with output  $V$  and effect  $E$

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- (1) **Syntactic** techniques
- (2) **Semantic** techniques

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generally inductive arguments

easy to refute observational equivalences;  
hard to prove them!



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use the syntax and the  $\sim$  relations directly;  
generally inductive arguments

easy to refute observational equivalences;  
hard to prove them!

build semantic models  
and study those instead

easier to prove observational equivalences;  
hard to refute them!

# Coming up next

1. Introduce an idealised functional programming language
  2. Explain its semantic interpretation in CCCs
- 

3. Introduce differentiable programming
4. Explain the interpretation in Diff

# Cartesian closed categories (CCCs)

**def:** a **cartesian closed category**  $(\mathbb{C}, \times, 1, \Rightarrow)$  is a category  $\mathbb{C}$   
 with finite products  $(\times, 1)$   
 and a right adjoint  $A \Rightarrow (-)$  for every  $(-) \times A$

$$\mathbb{C}(X, A_1 \times A_2) \cong \mathbb{C}(X, A_1) \times \mathbb{C}(X, A_2)$$

$$f \mapsto (\pi_1 \circ f, \pi_2 \circ f)$$

$$\langle f_1, f_2 \rangle \leftarrow f$$

$$\langle f_1, f_2 \rangle(x) = (f_1 x, f_2 x)$$

$$\mathbb{C}(X \times A, B) \cong \mathbb{C}(X, A \Rightarrow B)$$

$$f \mapsto \Lambda(f) \quad \Lambda(f)(x) = f(x, -)$$

$$\text{eval} \circ (f \times A) \leftarrow f$$

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$$f \mapsto (\pi_1 \circ f, \pi_2 \circ f) \quad \text{projections}$$

$$\text{pairing} \quad \langle f_1, f_2 \rangle \leftarrow (f_1, f_2)$$

$$\langle f_1, f_2 \rangle = \lambda x . (f_1 x, f_2 x)$$

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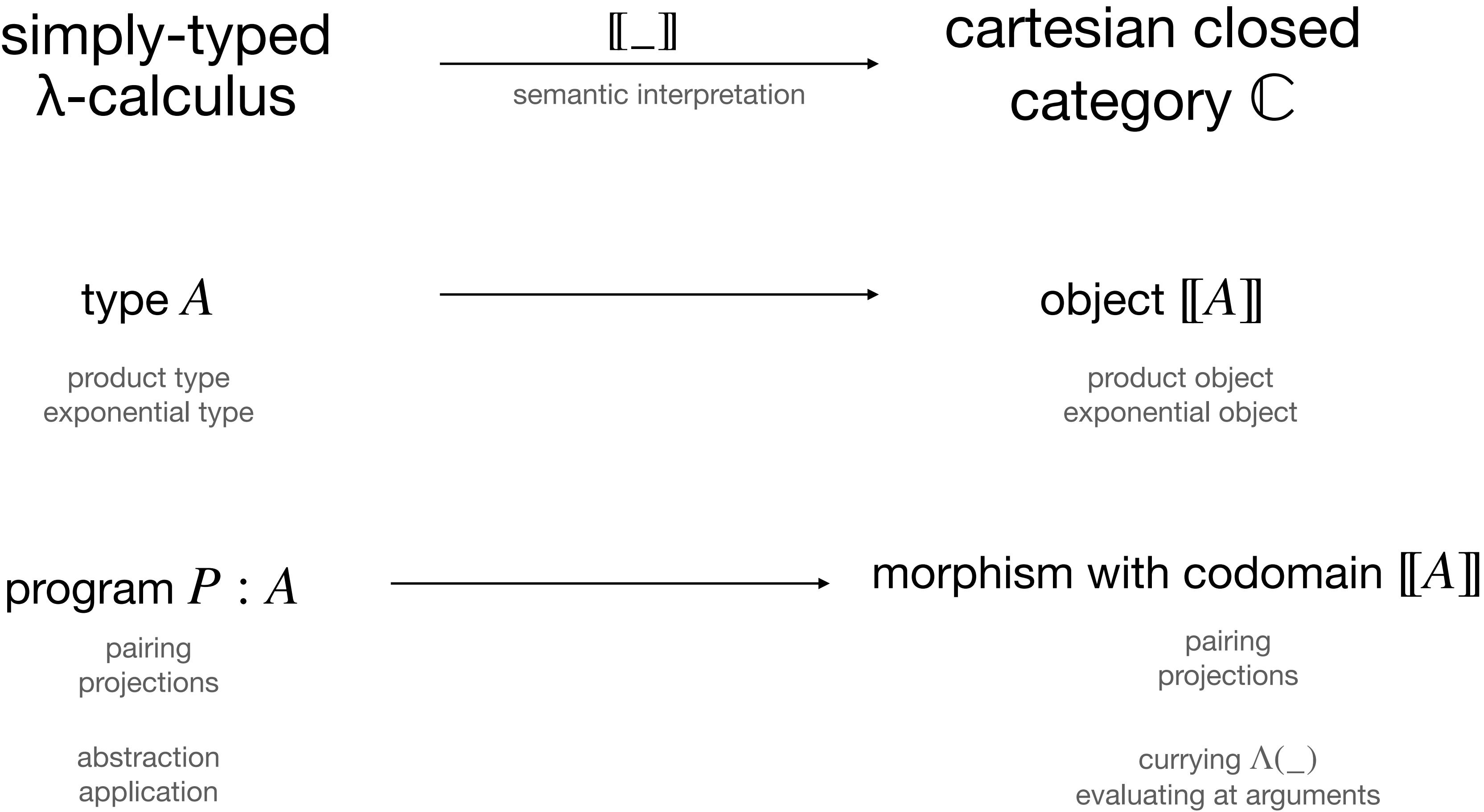
abstraction

$$\text{eval} \circ (f \times A) \leftarrow f$$

$$\text{eval} = \lambda(f, x) . f(x) \quad \text{application}$$

$$\text{eval} \circ (f \times A) = \lambda(x, a) . f(x)(a)$$

# Semantic interpretation



# Meanings for types in a CCC

Types  $\ni A, B ::= \text{nat} \mid \text{bool} \mid A \times B \mid A \rightarrow B$

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$[[\text{nat}]] := \mathbb{N}$   
 $[[\text{bool}]] := 2$

chosen objects  
eg  $2 := 1 + 1$ ,  $\mathbb{N} :=$  a natural numbers object

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$\llbracket A \times B \rrbracket := \llbracket A \rrbracket \times \llbracket B \rrbracket$

$\llbracket A \rightarrow B \rrbracket := (\llbracket A \rrbracket \Rightarrow \llbracket B \rrbracket)$

$\llbracket \text{nat} \rightarrow \text{bool} \rrbracket := (\mathbb{N} \Rightarrow 2)$

$\llbracket \text{bool} \rightarrow \text{bool} \rrbracket := (2 \Rightarrow 2)$

$\vdots$



# Meanings for terms in a CCC

handling free variables

no free variables

**plus** :  $\text{nat} \times \text{nat} \rightarrow \text{nat}$

assigns something of type  $\text{nat}$  whenever we give  $P : \text{nat} \times \text{nat}$

so  $\llbracket \text{plus} \rrbracket$  is a map  $\llbracket \text{nat} \rrbracket \times \llbracket \text{nat} \rrbracket \rightarrow \llbracket \text{nat} \rrbracket$ ;  
equivalently, a map  $1 \rightarrow (\llbracket \text{nat} \rrbracket \times \llbracket \text{nat} \rrbracket) \Rightarrow \llbracket \text{nat} \rrbracket$

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$b, n$  and  $m$  free

**if**( $b, n, m$ ) :  $\text{nat}$

assigns something of type  $\text{nat}$  whenever we give  $b : \text{bool}, n : \text{nat}$  and  $m : \text{nat}$

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$P : B$  with free variables  $(x_i : A_i)_{i=1, \dots, n}$  has  
interpretation  $\llbracket P \rrbracket : \prod_{i=1}^n \llbracket A_i \rrbracket \rightarrow \llbracket B \rrbracket$

assigns  $a_i \in \llbracket A_i \rrbracket$  to each  $x_i : A_i$   
eg  $\llbracket \text{if} \rrbracket(0, 2, 3) = 2$

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for  $P : B$  with no free variables,  
 $\llbracket P \rrbracket : 1 \rightarrow \llbracket B \rrbracket$

so eg  $P : A \rightarrow B$  is identified with an element of  $(\llbracket A \rrbracket \Rightarrow \llbracket B \rrbracket)$

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$P : B$  with free variables  $(x_i : A_i)_{i=1,\dots,n}$   
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Fix an interpretation  $\llbracket c \rrbracket$  for each primitive  $c$

For  $P : B$  with no free variables,  $\llbracket P \rrbracket \in \llbracket B \rrbracket$ :

$$\begin{aligned} \llbracket \pi_i(P) \rrbracket &= \left( i\text{th projection out } \llbracket P \rrbracket \right) \in \llbracket B_i \rrbracket \\ \llbracket \langle P_1, P_2 \rangle \rrbracket &= \left( \llbracket P_1 \rrbracket, \llbracket P_2 \rrbracket \right) \in \llbracket B_1 \rrbracket \times \llbracket B_2 \rrbracket \\ \llbracket P(Q) \rrbracket &= \left( \llbracket P \rrbracket \right) \left( \llbracket Q \rrbracket \right) \in \llbracket C \rrbracket \\ \llbracket \lambda x . P \rrbracket &= \lambda b . \llbracket P \rrbracket( b) \in \llbracket B \rrbracket \Rightarrow \llbracket C \rrbracket \end{aligned}$$



# Meanings for terms in Set

Fix an interpretation  $\llbracket c \rrbracket$  for each primitive  $c$

For  $\vec{a} \in \prod_{i=1}^n \llbracket A_i \rrbracket$

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$$\llbracket \langle P_1, P_2 \rangle \rrbracket(\vec{a}) = \left( \llbracket P_1 \rrbracket(\vec{a}), \llbracket P_2 \rrbracket(\vec{a}) \right) \in \llbracket B_1 \rrbracket \times \llbracket B_2 \rrbracket$$

$$\llbracket P(Q) \rrbracket(\vec{a}) = \left( \llbracket P \rrbracket(\vec{a}) \right) \left( \llbracket Q \rrbracket(\vec{a}) \right) \in \llbracket C \rrbracket$$

$$\llbracket \lambda x . P \rrbracket(\vec{a}) = \lambda b . \llbracket P \rrbracket(\vec{a}, b) \in \llbracket B \rrbracket \Rightarrow \llbracket C \rrbracket$$

# Meanings for terms in a CCC

$P : B$  with free variables  $(x_i : A_i)_{i=1,\dots,n}$   
 has interpretation  
 $\llbracket P \rrbracket : \prod_{i=1}^n \llbracket A_i \rrbracket \rightarrow \llbracket B \rrbracket$

assigns  $a_i \in \llbracket A_i \rrbracket$  to each  $x_i : A_i$

Fix an interpretation  $\llbracket c \rrbracket$  for each primitive  $c$

Then:

$$\llbracket \pi_i(P) : B_i \rrbracket = \pi_i \circ \llbracket P : B_1 \times B_2 \rrbracket$$

$$\llbracket \langle P_1, P_2 \rangle : B_1 \times B_2 \rrbracket = \langle \llbracket P_1 : B_1 \rrbracket, \llbracket P_2 : B_2 \rrbracket \rangle \quad \langle f_1, f_2 \rangle(x) = (f_1 x, f_2 x)$$

$$\llbracket P(Q) : C \rrbracket = \text{eval} \circ \langle \llbracket P : B \rightarrow C \rrbracket, \llbracket Q : B \rrbracket \rangle$$

$$\llbracket \lambda x . P : B \rightarrow C \rrbracket = \Lambda(\llbracket P : C \rrbracket)$$

$$\Lambda(f) = \lambda x . f(x, \_)$$

$$\text{eval} \circ (f \times A) = \lambda(x, a) . f(x)(a)$$

# Soundness of the interpretation

$P : B$  with free variables  $(x_i : A_i)_{i=1,\dots,n}$   
has interpretation  
 $\llbracket P \rrbracket : \prod_{i=1}^n \llbracket A_i \rrbracket \rightarrow \llbracket B \rrbracket$

assigns  $a_i \in \llbracket A_i \rrbracket$  to each  $x_i : A_i$

for any CCC  $\mathbb{C}$  and any choice of base types and constants,

$$P =_{\beta\eta} Q \implies \llbracket P \rrbracket = \llbracket Q \rrbracket$$

in an **adequate** model,  $\llbracket P \rrbracket = \llbracket Q \rrbracket \implies P \simeq_{\text{obs}} Q$

in fact, simply-typed  $\lambda$ -calculus modulo  $=_{\beta\eta}$  is

a sound and complete logic for CCCs



# What does programming language theory study?

We want programs that are:

efficient, fast, and correct

We ask:

- (1) How should we think about programs?
- (2) When are programs interchangeable?

Two notions of equality:

$\beta\eta$ -equality  $=_{\beta\eta}$ : the congruence generated by  $\sim_{\beta} \cup \sim_{\eta}$

observational equivalence:  $P \simeq_{\text{obs}} Q$  iff whatever program  $C[_]$  of type `bool` or `nat` we put them in,  $C[P]$  and  $C[Q]$  have the same behaviour

# What does denotational semantics study?

We want programs that are:

efficient, fast, and correct

We ask:

- (1) How should we think about programs?
- (2) When are programs interchangeable?

terms in some version of  
simply-typed  $\lambda$ -calculus  
interpreted in a CCC

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use adequate models to reason about  
observational equivalence of programs

adequacy:  $\llbracket P \rrbracket = \llbracket Q \rrbracket \implies P \simeq_{\text{obs}} Q$

# Some example interpretations

languages with no effects

plain CCCs

languages with printing,  
global memory, exceptions

CCCs with a (strong)  
monad

the monad  $T$  describes the  
effect, eg  $(-)+1$  or  $S^* \times (-)$

languages with local memory

presheaf  
categories

think: programs parametrised by  
possible states of the memory

languages with recursion

order-enriched  
categories

$\leq$  models ‘how defined’ a function is

each recursive call goes up the order;  
the whole loop is then a fixpoint

looping forever modelled by a bottom element

# How should we think about programs?

```
fun add(x, y):  
  return (x + y)
```

```
fun divide(x, y):  
  return (x / y)
```

```
fun print_and_return(x):  
  print "hello";  
  return x;
```

```
let b = flip(p);  
return b;
```

```
normalise(  
  let x = sample(bernoulli(0.8));  
  let r = (if x then 10 else 3);  
  observe 0.45 from exponential(r)  
  return(x)  
)
```

a function  $\mathbb{N} \times \mathbb{N} \rightarrow \mathbb{N}$

a function  $\mathbb{Z} \times \mathbb{Z}_{\neq 0} \rightarrow \mathbb{Q}$

a function  $\mathbb{Z} \times \mathbb{Z} \rightarrow \mathbb{Q} + \{\text{fail}\}$

a function  $\mathbb{N} \rightarrow \{a, b, \dots, z\}^* \times \mathbb{N}$   
 $x \mapsto (\text{hello}, x)$

a probability distribution on  
 $\{\text{true}, \text{false}\}$

some measurable function (??)

# Coming up next

1. Introduce an idealised functional programming language
  2. Explain its semantic interpretation in CCCs
- 

3. Introduce differentiable programming
4. Explain the interpretation in Diff



high-dimensional  
input

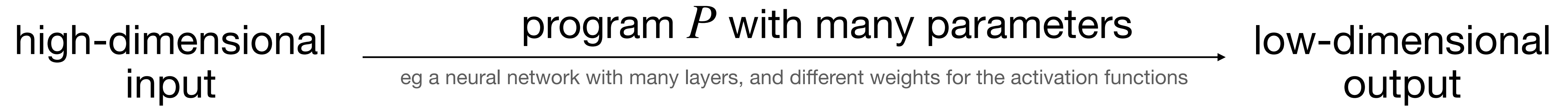


—————→ cat

low-dimensional  
output



—————→ dog



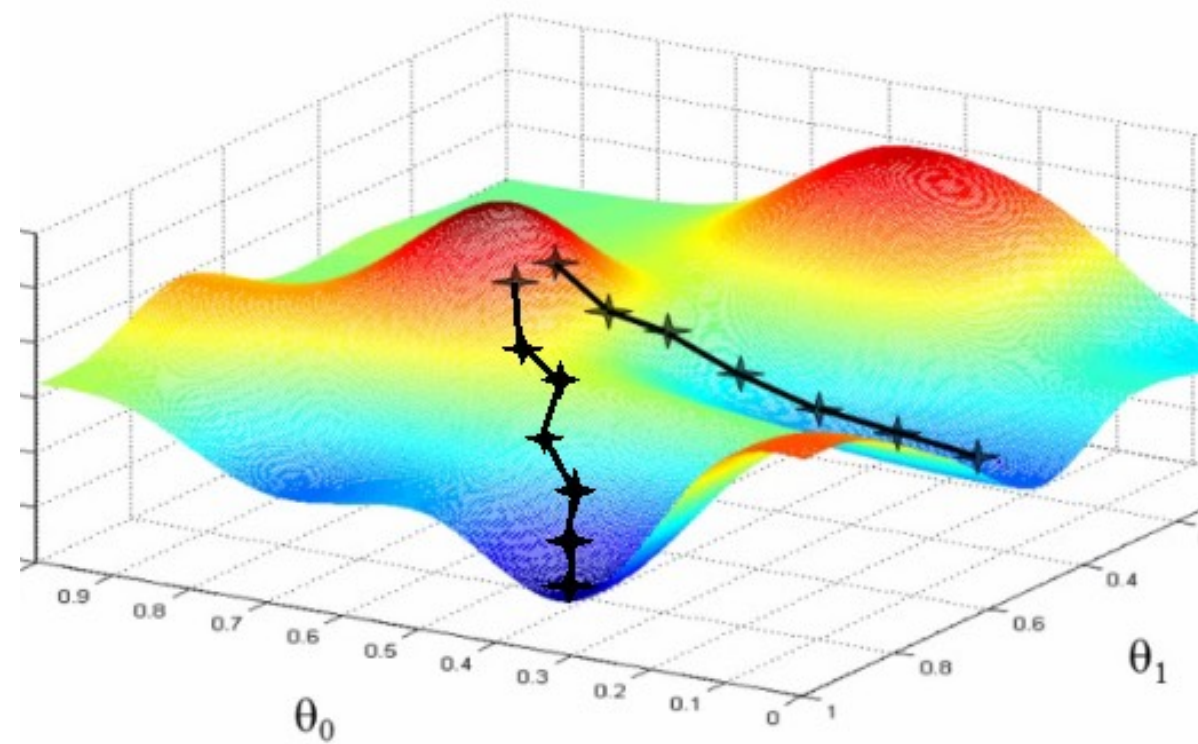


high-dimensional  
input

program  $P$  with many parameters

eg a neural network with many layers, and different weights for the activation functions

low-dimensional  
output



[https://www.youtube.com/watch?v=5u4G23\\_Oohl](https://www.youtube.com/watch?v=5u4G23_Oohl)

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aim: optimise the parameters for  $P$

so that, eg, it classifies cats as cats as often as possible

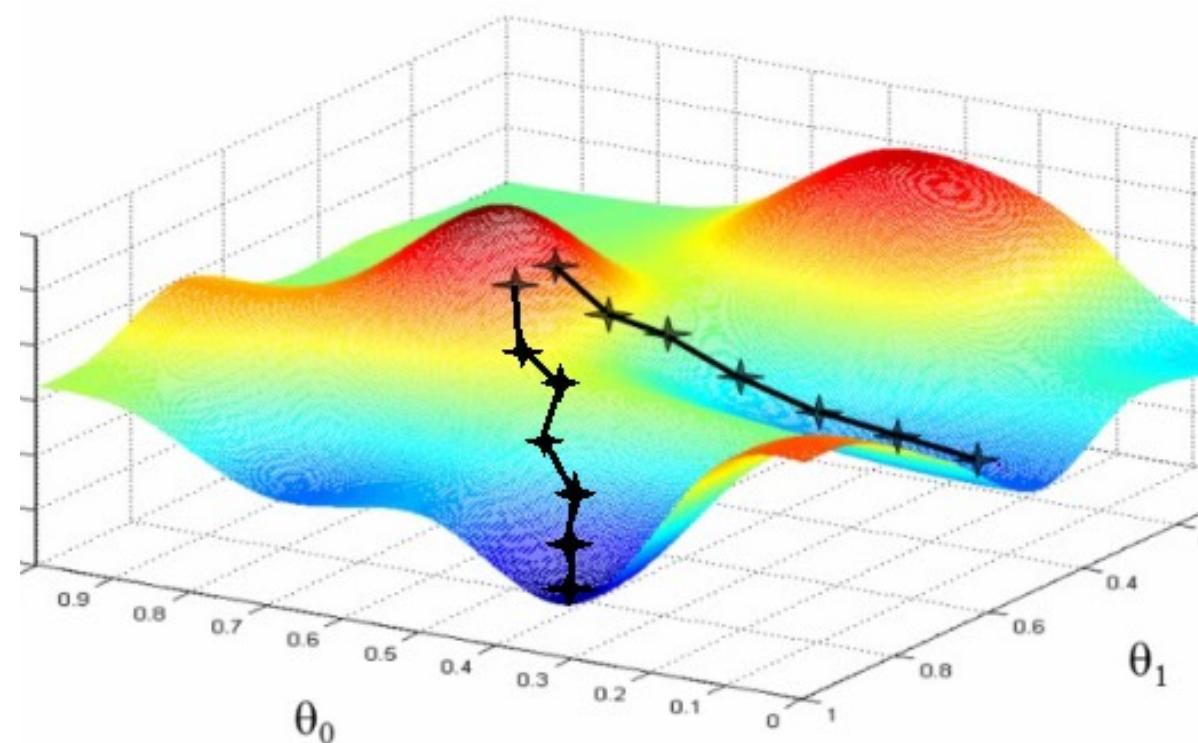
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numerically, but it's  
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can we write an algorithm to calculate derivatives exactly?

...and can we prove this is **correct**?

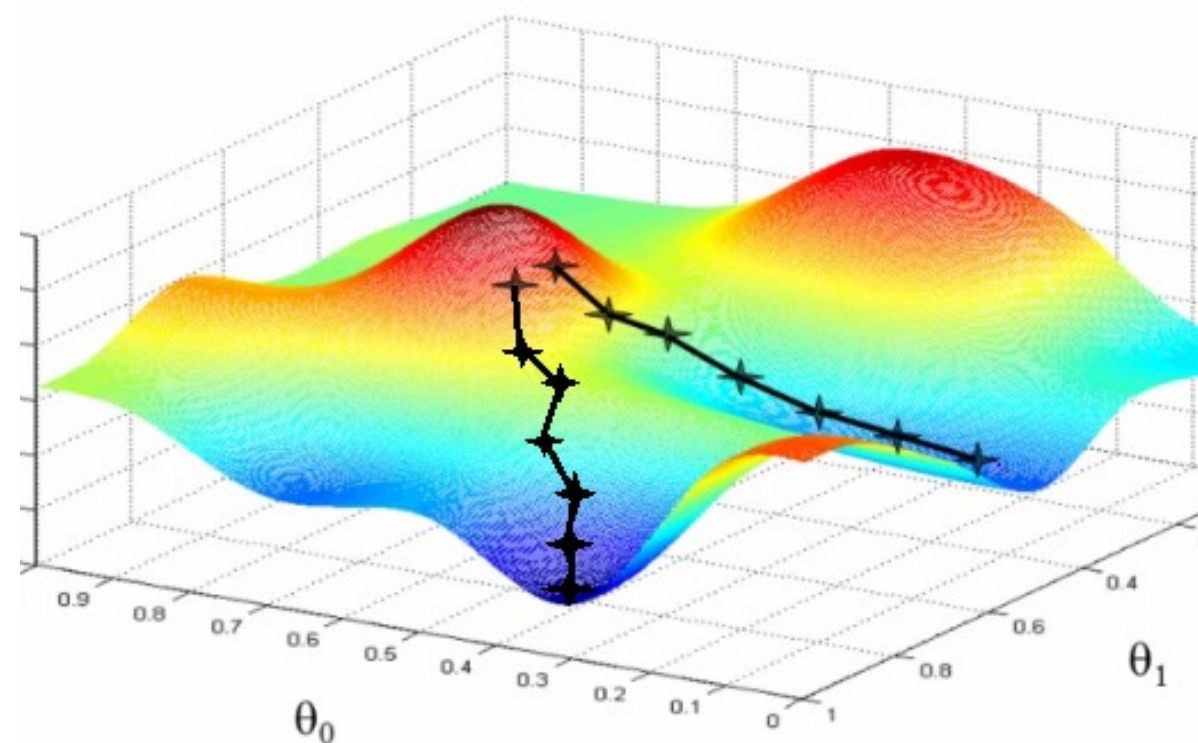
“forward AD”,  
“reverse AD”, etc

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**differentiable programming** (TensorFlow, PyTorch, etc)

= languages where you can automatically  
compute the derivative of any program

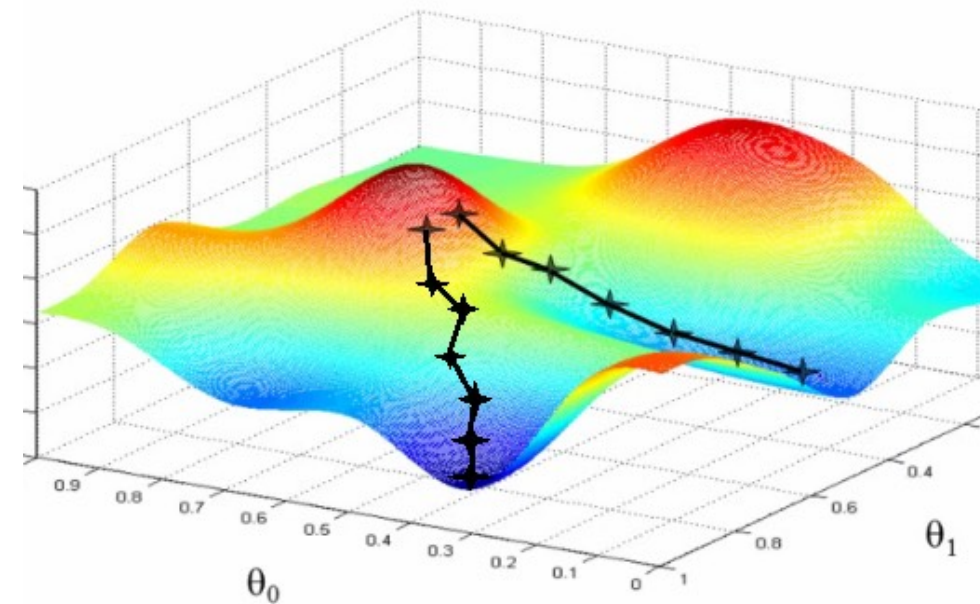


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= a serious bottleneck

from the denotational semantics POV:

(1)  $\llbracket P \rrbracket$  is some smooth function  $\mathbb{R}^n \rightarrow \mathbb{R}$

(2) aim: to algorithmically define a program  $D(P)$

and prove that  $\llbracket D(P) \rrbracket = D(\llbracket P \rrbracket)$

essentially, using the chain rule  
and “dual numbers”



# Proving correctness of automatic differentiation

[Huot, Staton, Vakar]

a natural suggestion:

- (1) we only care about the programs returning a value, ie those of type `real`
- (2) take simply-typed  $\lambda$ -calculus + primitives for real numbers etc
- (3) a program  $P : \text{real}$  is meant to represent a smooth function  $\mathbb{R}^n \rightarrow \mathbb{R}$
- (4) define  $D(P)$  by induction on the simply-typed  $\lambda$ -calculus  
and check  $\llbracket D(P) \rrbracket = D(\llbracket P \rrbracket)$

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$$\begin{aligned}\vec{D}(x) &\stackrel{\text{def}}{=} x & \vec{D}(\underline{c}) &\stackrel{\text{def}}{=} \langle \underline{c}, 0 \rangle \\ \vec{D}(t + s) &\stackrel{\text{def}}{=} \mathbf{case} \vec{D}(t) \mathbf{of} \langle x, x' \rangle \rightarrow \mathbf{case} \vec{D}(s) \mathbf{of} \langle y, y' \rangle \rightarrow \langle x + y, x' + y' \rangle \\ \vec{D}(t * s) &\stackrel{\text{def}}{=} \mathbf{case} \vec{D}(t) \mathbf{of} \langle x, x' \rangle \rightarrow \mathbf{case} \vec{D}(s) \mathbf{of} \langle y, y' \rangle \rightarrow \langle x * y, x * y' + x' * y \rangle \\ \vec{D}(\varsigma(t)) &\stackrel{\text{def}}{=} \mathbf{case} \vec{D}(t) \mathbf{of} \langle x, x' \rangle \rightarrow \mathbf{let} y = \varsigma(x) \mathbf{in} \langle y, x' * y * (1 - y) \rangle \\ \vec{D}(\lambda x. t) &\stackrel{\text{def}}{=} \lambda x. \vec{D}(t) & \vec{D}(t s) &\stackrel{\text{def}}{=} \vec{D}(t) \vec{D}(s) & \vec{D}(\langle t_1, \dots, t_n \rangle) &\stackrel{\text{def}}{=} \langle \vec{D}(t_1), \dots, \vec{D}(t_n) \rangle\end{aligned}$$

from *Correctness of Automatic  
Differentiation via Diffeologies and  
Categorical Gluing*



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ie. we interpret in the category of cartesian spaces ( $= \mathbb{R}^n$  for some  $n$ ) and smooth maps

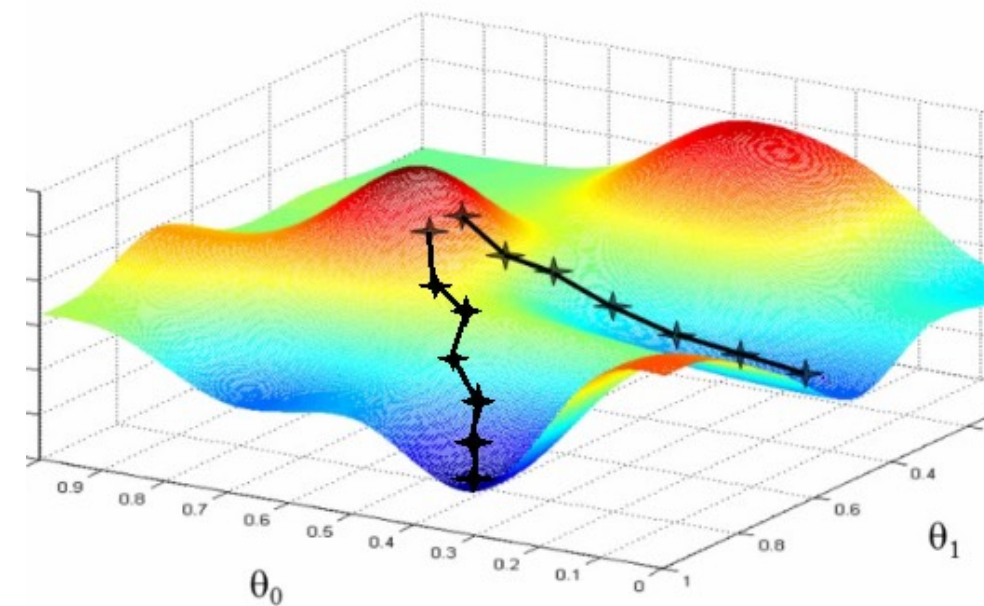
but this category is not cartesian closed! and even  $P : \text{real}$  may contain lambdas,  
eg  $(\lambda f. \lambda x. f(x + x)) (\text{exp})(2)$

high-dimensional  
input

program  $P$  with many parameters

eg a neural network with many layers, and different weights for the activation functions

low-dimensional  
output



[https://www.youtube.com/watch?v=5u4G23\\_OoI](https://www.youtube.com/watch?v=5u4G23_OoI)

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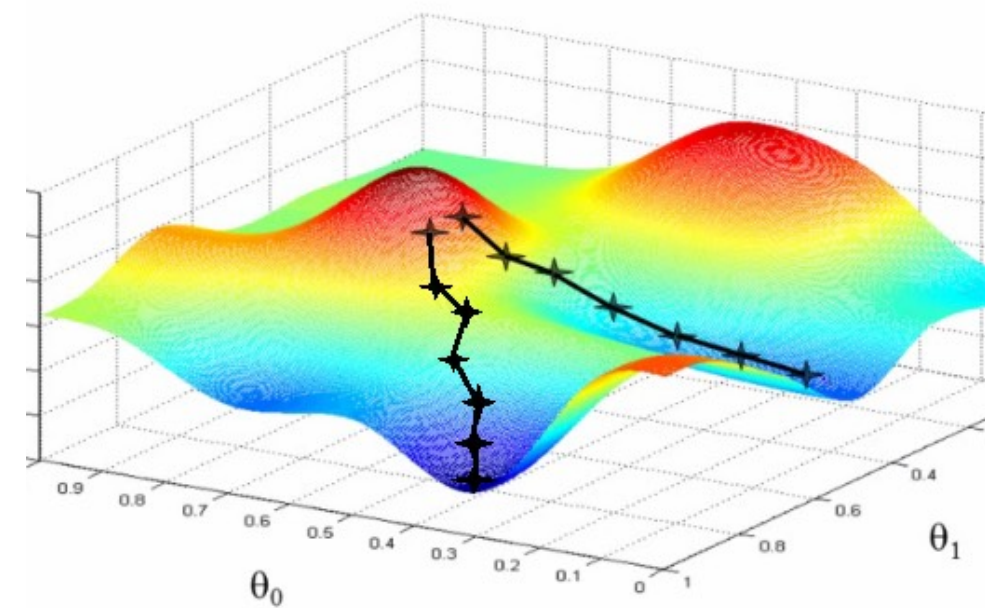
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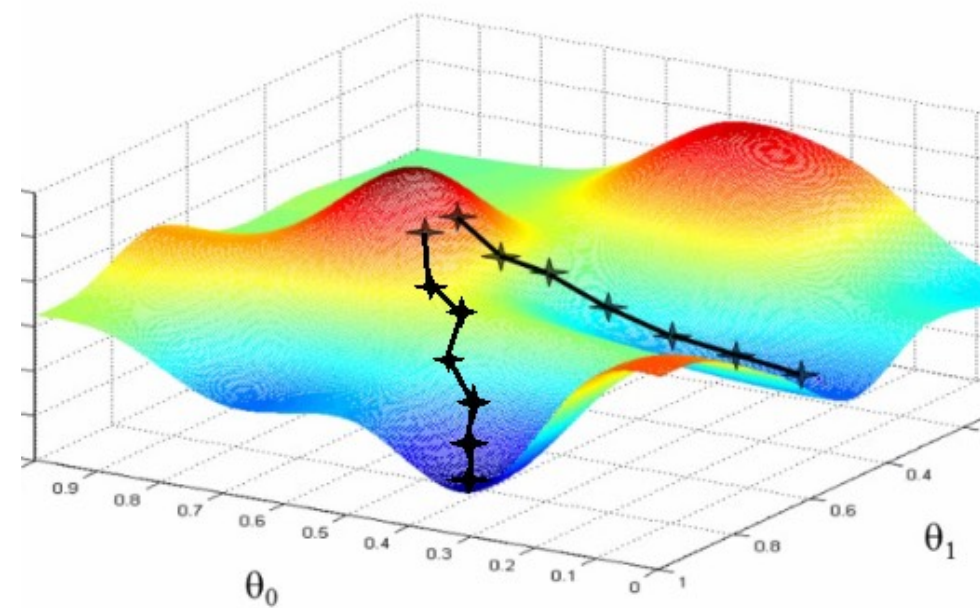
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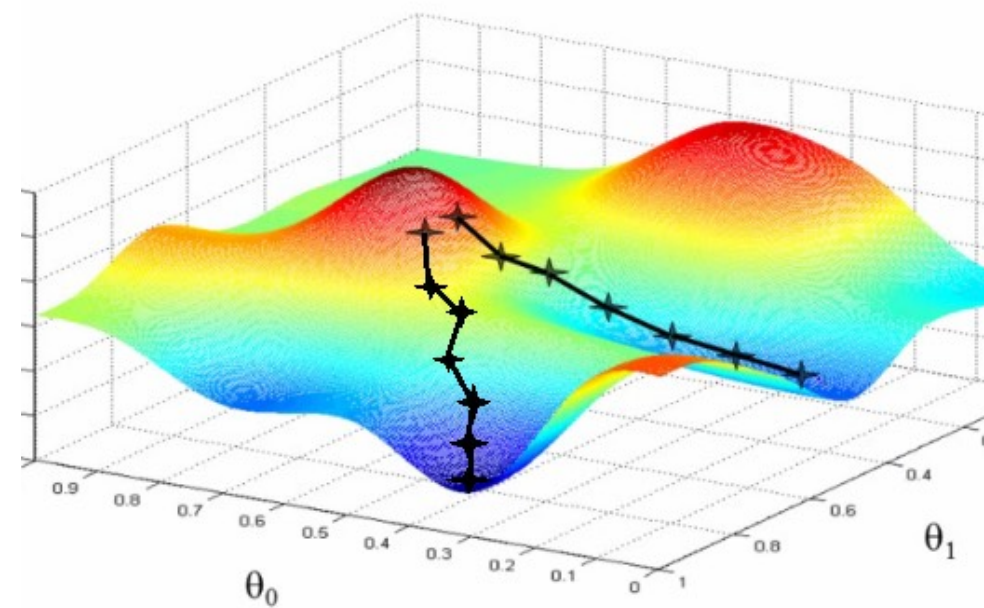
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we need a CCC that supports some notion of derivative



[https://www.youtube.com/watch?v=5u4G23\\_Oohl](https://www.youtube.com/watch?v=5u4G23_Oohl)



# The category of diffeological spaces

Diff is a nice semantic model! It has:

- (1) cartesian closure = can model product and function types
- (2) a full embedding  $\mathbf{CartSp} \rightarrow \mathbf{Diff}$  = conservativity over the natural model,  
good ways to interpret reals etc
- (3) coproducts = can interpret sum types ( $\sim$  disjoint unions)
- (4) initial algebras for endofunctors  
= can interpret lists and similar inductive types



# Proving correctness of automatic differentiation

[Huot, Staton, Vakar]

The strategy:

- (a) interpret programs  $P$  in Diff
- (b) prove that  $\llbracket P : \text{real} \rrbracket$  always lands in CartSp, even if it has lambdas
- (c) prove a correctness property for differentiation, at every type
- (d) deduce correctness of the  $D( - )$  algorithm at type real

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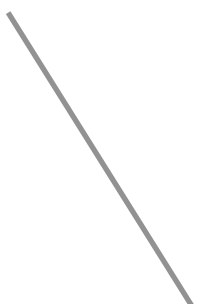
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So we can prove facts about derivatives of programs,  
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And, at type `real` the interpretation coincides with the natural one

# Diff at work for semantics

- (1) An analogy
- (2) Adding recursion
- (3) Cutting down the model: full abstraction

# Probabilistic programming

Idea:

- (1) programs express statistical models,  
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How do we interpret probabilistic programs?

What is a good semantic model?

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probabilistic programs  
'should' be interpreted by  
**measurable functions**

but Meas is not cartesian closed!

= no way to interpret higher-order functions

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# Quasi-Borel spaces [Heunen, Kammar, Moss, Scibior, Staton, Vakar, Yang]

$\text{Diff}$  = category of concrete sheaves on cartesian manifolds

$\text{QBS}$  = category of concrete sheaves on standard Borel spaces

always a quasi-topos, in particular a CCC

$\text{QBS}$  provides a good semantic model for probabilistic programming,  
just as  $\text{Diff}$  provides a good semantic model for differentiable programming

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- (2) Adding recursion
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# Adding recursion to simply-typed $\lambda$ -calculus

[Scott, Plotkin,...]

plus :  $\mathbb{N} \times \mathbb{N} \rightarrow \mathbb{N}$  is the least map satisfying

$$\text{plus}(x, 0) = x$$

$$\text{plus}(x, y + 1) = \text{plus}(x, y) + 1$$

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---	--

$$\text{fix}(M) =_{\beta\eta} M \ (\text{fix}(M))$$

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# Adding recursion to simply-typed $\lambda$ -calculus

[Scott, Plotkin,...]

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- (1) every chain  $x_0 \leq x_1 \leq \dots \leq x_n \leq \dots$  has a least upper bound
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Forms a CCC, and every map has a least fixed point

by Tarski's fixpoint theorem

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Can extend correctness  
results for AD to languages  
with recursion!

# Diff at work for semantics

- (1) An analogy: quasi-Borel spaces [Heunen, Kammar, Moss, Scibior, Staton, Vakar, Yang]
- (2) Adding recursion [Vakar] [Vakar, Kammar, Staton]
- (3) Cutting down the model: full abstraction

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[Kammar, Katsumata, S.]

Given  $P \simeq_{\text{ctx}} Q$ , can we deduce  $\llbracket P \rrbracket = \llbracket Q \rrbracket$ ?

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objects = diffeological spaces paired with a family of relations  
morphisms = smooth maps preserving the relations

(new model)



preserves primitives and products,  
but **not** exponentials

Diff

choose the class of relations intensionally  
so maps preserving the relation are definable

# Diff at work for semantics

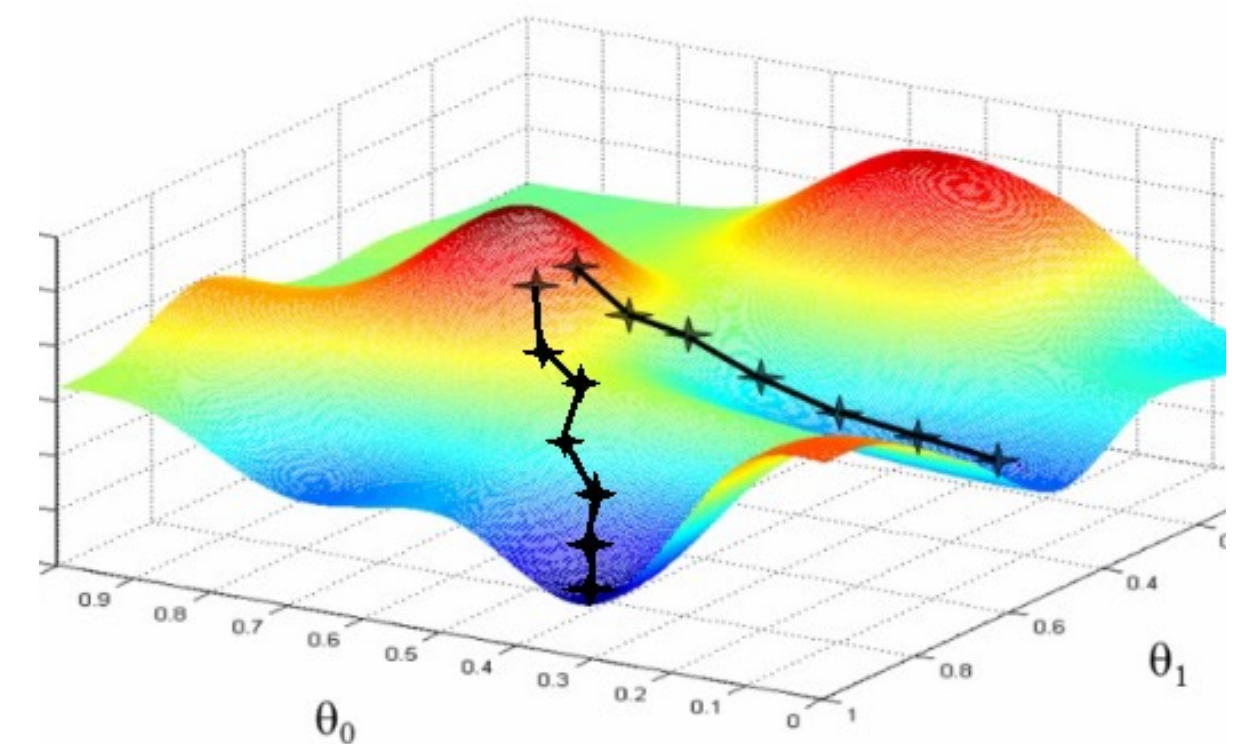
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## Denotational semantics:

- idealised functional programming language  
= simply-typed  $\lambda$ -calculus (+ extensions)
- interchangeability of programs  
= observational equivalence finer than equality-on-arguments!
- interpret programs in CCCs (+ extensions)

Diff is a good model for studying  
automatic differentiation of programs

$$P \mapsto D(P)$$



[https://www.youtube.com/watch?v=5u4G23\\_Oohl](https://www.youtube.com/watch?v=5u4G23_Oohl)